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**CLAIMS**

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**[Claim(s)]**

[Claim 1]A feeding member which feeds paper to this manuscript sheaf and is conveyed to separating mechanism when it is provided in a manuscript sheaf characterized by comprising the following laid on a manuscript mounting base up to a manuscript sheaf so that it may be contacted and isolated, and this manuscript sheaf is contacted, An automatic manuscript conveying machine with which a tip part of a manuscript was provided with a regulating member which regulates that a manuscript sheaf moves to the transportation direction downstream of a manuscript rather than a prescribed position on a manuscript mounting base in contact with a time of being provided in said manuscript mounting base so that contact and isolation are possible, and contacting a manuscript mounting base.

Establishing one driving means driven so that said feeding member and a regulating member may be moved to contact and a separated location, this driving means is a drive motor. Member turning which is provided in an outgoing end of each system of a transmission mechanism which divides driving force of this drive motor into two lines, and transmits it, and this transmission mechanism, and moves said feeding member and a regulating member to contact and a separated location according to a drive of each system of this transmission mechanism.

[Claim 2]When said drive motor rotates normally, while driving force of this drive motor is transmitted, one system of said transmission mechanism, The automatic manuscript conveying machine according to claim 1, wherein a system of another side of said transmission mechanism is constituted so that driving force of this drive motor may be transmitted, when said drive motor is reversed, and it switches contact and a separated location of said feeding member and a regulating member with reciprocal rotation of this drive motor.

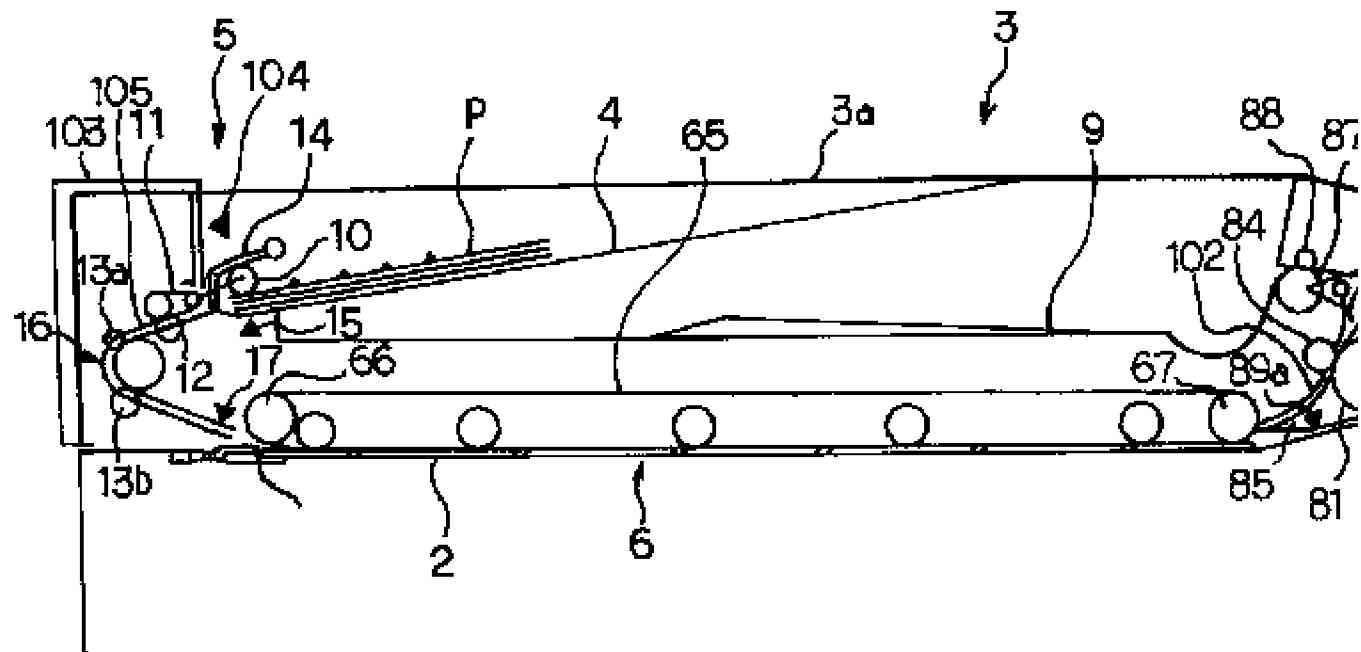
[Claim 3]Said transmission mechanism equips a position which branches driving force of said

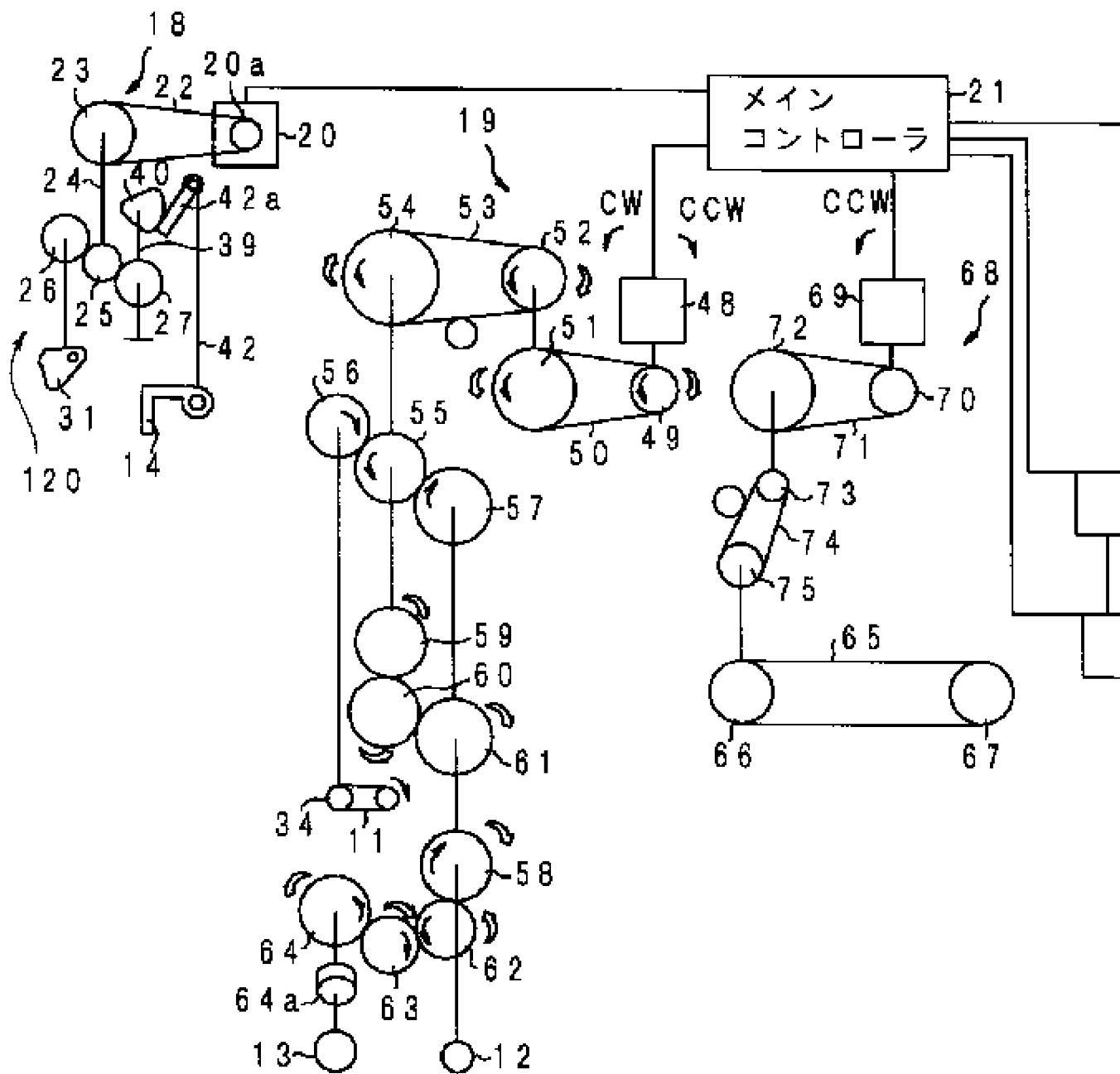
drive motor for each system at least with a gear of a couple which has a one-way clutch, When said drive motor rotates normally, while rotating one side of said gear and transmitting driving force to either one of a feeding member and a regulating member. The automatic manuscript conveying machine according to claim 2 characterized by making it not transmit driving force to any of a feeding member and a regulating member, or another side, without rotating another side of a gear.

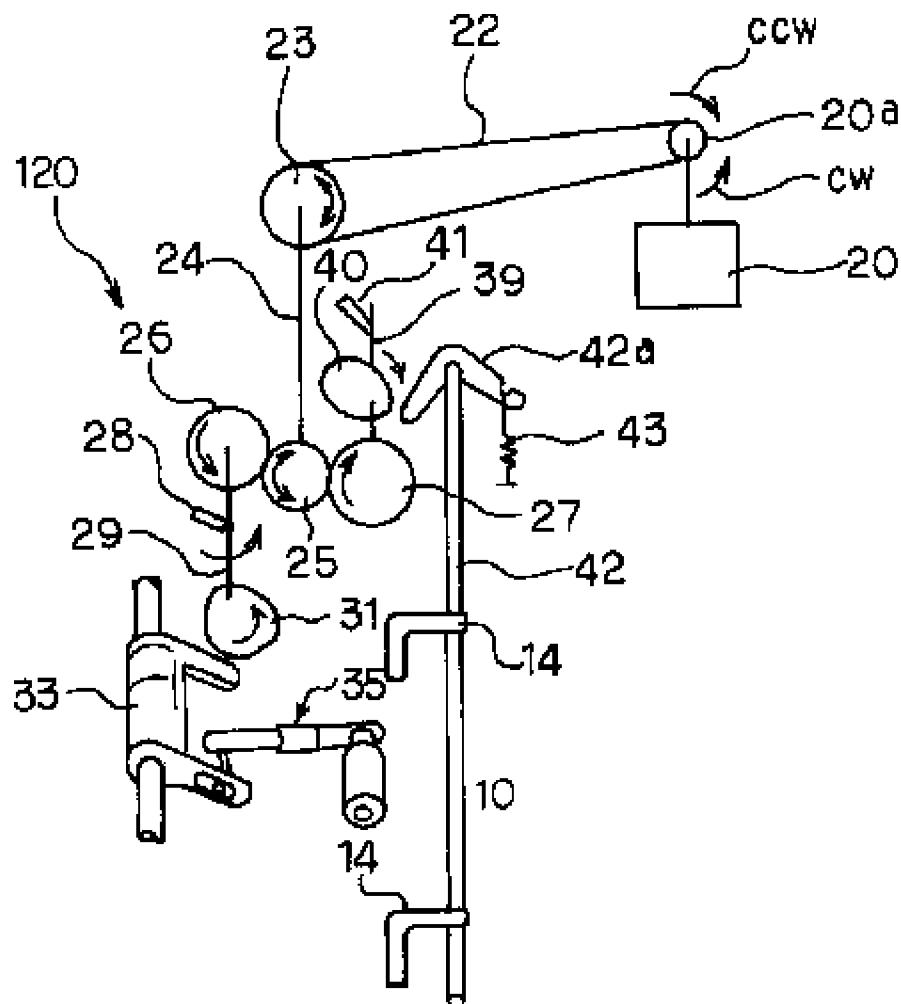
[Claim 4]The automatic manuscript conveying machine according to any one of claims 1 to 3, wherein a part of member which constitutes a transmission mechanism of a to [ from said drive motor / said feeding member ] is provided on a predetermined conveyance member which is allocated near the feeding member and feeds paper to a manuscript, and the same mind.

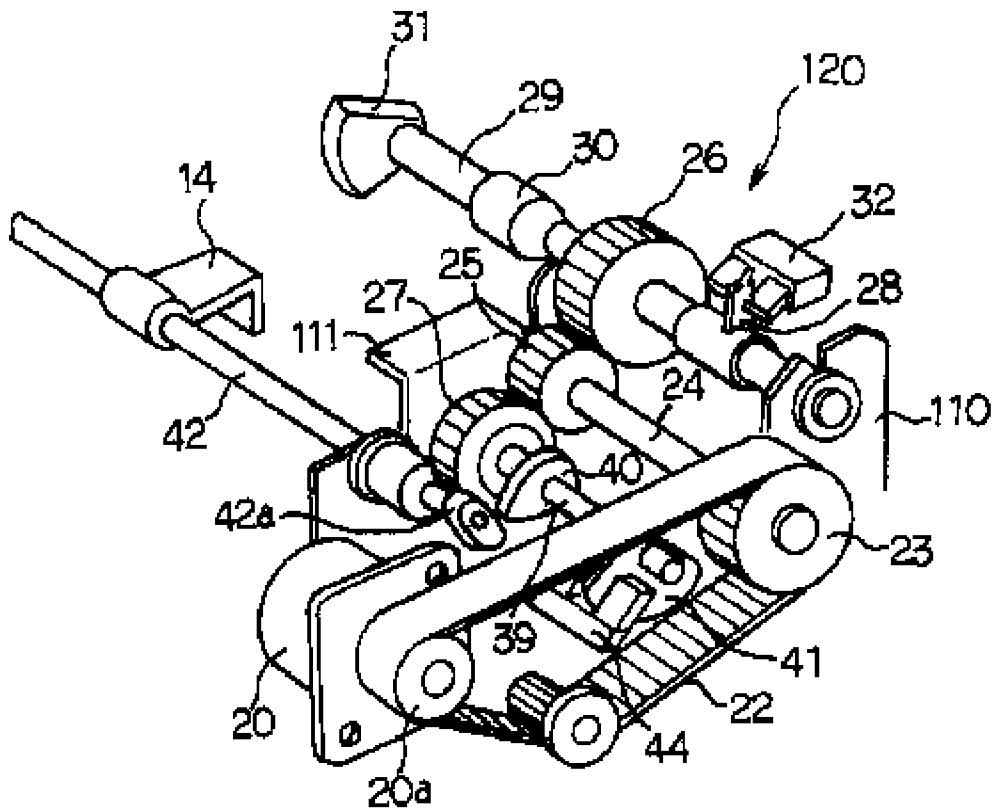
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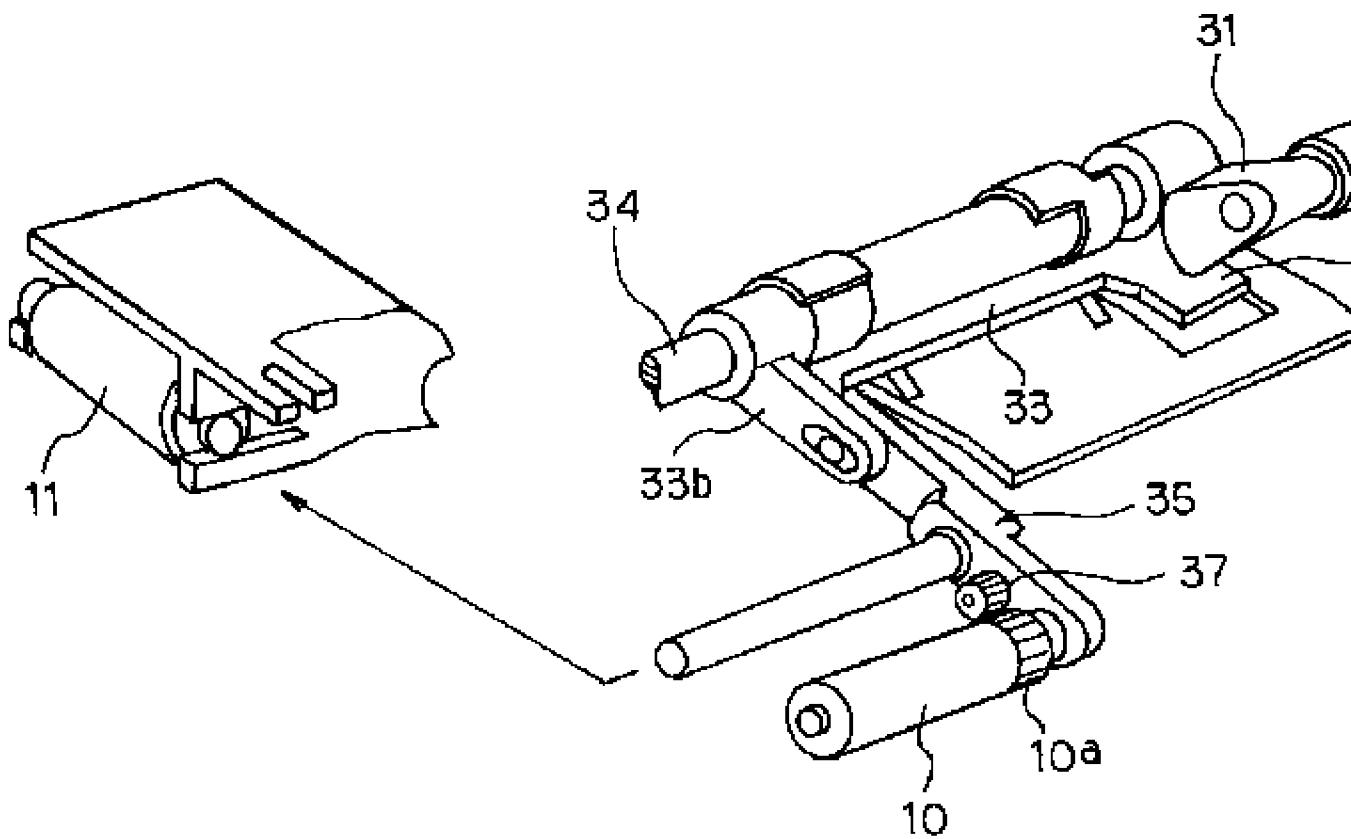
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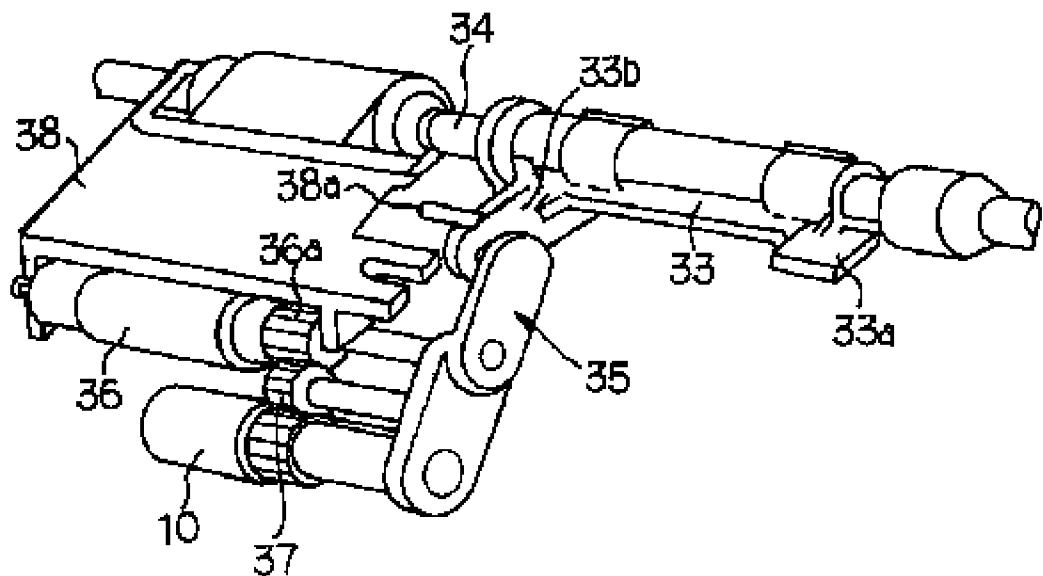




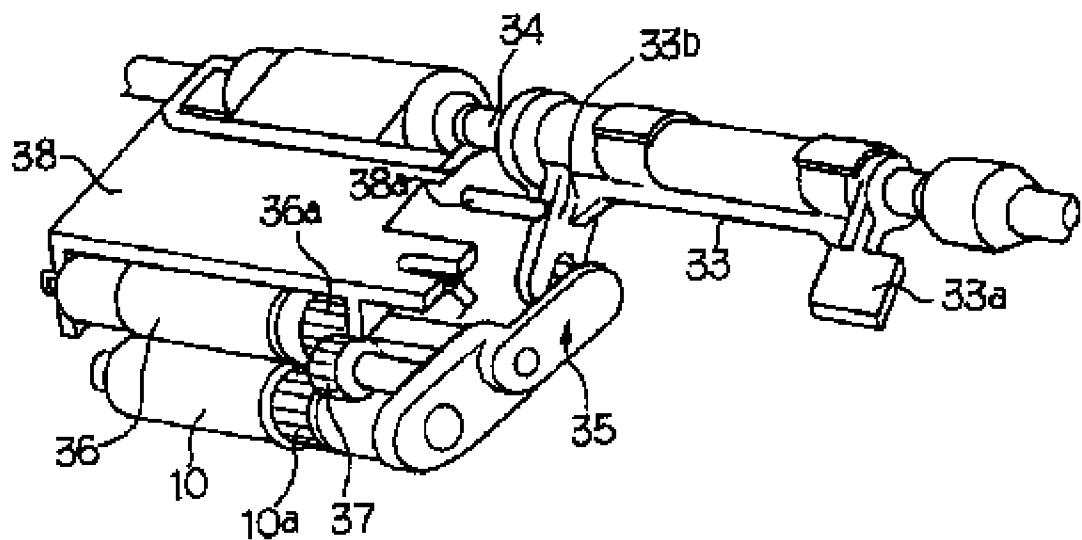




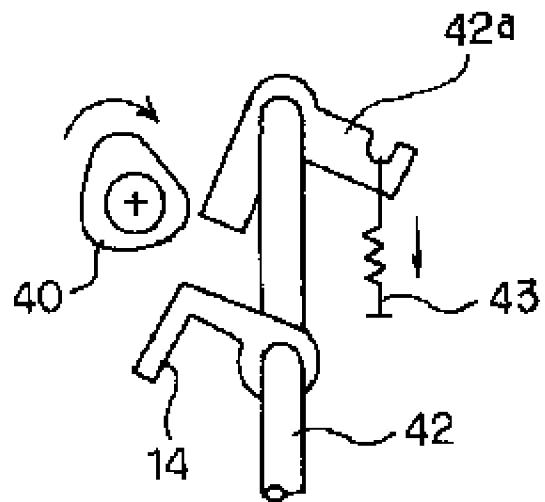
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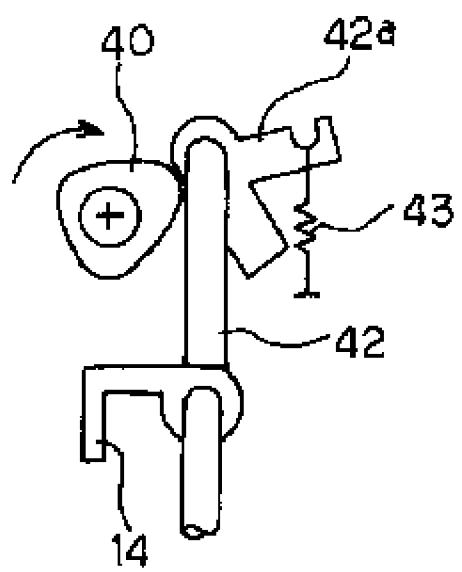
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(a)



(b)



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**DETAILED DESCRIPTION**

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**[Detailed Description of the Invention]****[0001]**

[Field of the Invention] This invention about the automatic manuscript conveying machine provided in image forming devices, such as a copying machine, a facsimile machine, and a printer, in detail, It is related with the automatic manuscript conveying machine provided with the regulating member which regulates that the tip part of the feeding member which feeds paper to the manuscript sheaf laid on the manuscript mounting base, and is conveyed to separating mechanism, and the manuscript laid in the manuscript mounting base contacts, and a manuscript sheaf moves to the transportation direction downstream of a manuscript rather than the prescribed position on a manuscript mounting base.

**[0002]**

[Description of the Prior Art] If it is in the automatic manuscript conveying machine (henceforth ADF) which is one of the image forming devices and which is carried in a copying machine recently, When setting the manuscript sheaf which becomes a manuscript tray from two or more manuscripts, in order to make the set location of this manuscript sheaf intelligible, or in order to prevent the set mistake of a manuscript, the stoper claw which tells the set location of a manuscript is formed.

[0003] This stoper claw is formed in a manuscript tray so that contact and isolation are possible, and the tip part of a manuscript regulates that a manuscript sheaf moves to the transportation direction downstream of a manuscript rather than the set location on a manuscript tray in contact with the time of contacting a manuscript tray.

It is isolated from a manuscript tray so that it may not become the hindrance of manuscript feeding, when a manuscript sheaf is set and a copy start button is operated, and when all the feedings of the manuscript laid in the manuscript tray are completed, a manuscript tray is contacted again.

[0004]On the other hand, when a stoper claw is isolated from a manuscript tray, there is a pickup roller which feeds paper to a manuscript from a manuscript tray in contact with a manuscript, and this pickup roller, In ADF of the type which dissociates from the upper part and feeds paper to a manuscript sheaf, it is provided up to a manuscript tray and contact and isolation are attained at the manuscript sheaf. Although there are some which move and contact the pickup roller side which the manuscript tray suspended in this manuscript tray upper part to the pickup roller allocated in such the upper part, Since the structure of a manuscript tray becomes complicated in order that a manuscript tray may move if it is in this thing, it is usually made to do contact and isolation of a pickup roller to a manuscript tray.

[0005]ON/OFF operation of the stoper claw and pickup roller which were mentioned above is carried out so that it may usually be contacted and isolated by a separate solenoid etc. at a manuscript tray. As this reason, the pickup koro is moved to the position which contacts a manuscript sheaf at the time of feeding of a manuscript, The manuscript which isolates and follows is prevented from separating from a manuscript sheaf, when a manuscript is separated by separating mechanisms, such as a separation belt and reverse koro, As opposed to carrying out frequently operation contacted and isolated to a manuscript sheaf as a manuscript sheaf is contacted again, in order to separate the manuscript sheaf which follows after separation of the manuscript to precede is completed, A stoper claw is moved to the position which contacts a manuscript tray at the time of the set of a manuscript, It is easy to control the direction driven by the separate solenoid etc. from a manuscript tray having dramatically little operation contacted and isolated as it is moved to the position isolated from the manuscript tray after feeding of a manuscript is started until it ends.

[0006]

[Problem(s) to be Solved by the Invention]However, since the stoper claw and the pickup roller were driven by the separate driving means if it was in conventional ADF, while part mark will increase, only the part had the problem that cost will increase. Then, as this invention drives a feeding member and a regulating member by one driving means, an object of this invention is to provide the automatic manuscript conveying machine which can prevent a manufacturing cost from increasing while being able to prevent the part mark of a driving means from increasing.

[0007]

[Means for Solving the Problem]In order that the invention according to claim 1 may solve an aforementioned problem, it is provided in a manuscript sheaf laid on a manuscript mounting base up to a manuscript sheaf so that it may be contacted and isolated, A feeding member which feeds paper to this manuscript sheaf and is conveyed to separating mechanism when this manuscript sheaf is contacted, It is provided in said manuscript mounting base so that

contact and isolation are possible, and a tip part of a manuscript equips with the following an automatic manuscript conveying machine with which a manuscript sheaf was provided with a regulating member which regulates moving to the transportation direction downstream of a manuscript rather than a prescribed position on a manuscript mounting base in contact with a time of contacting a manuscript mounting base.

Establishing one driving means driven so that said feeding member and a regulating member may be moved to contact and a separated location, this driving means is a drive motor.

A transmission mechanism which divides driving force of this drive motor into two lines, and transmits it.

Member turning which is provided in an outgoing end of each system of this transmission mechanism, and moves said feeding member and a regulating member to contact and a separated location according to a drive of each system of this transmission mechanism.

[0008]In that case, a manufacturing cost of an automatic manuscript conveying machine can be prevented from being able to set a driving source to one, as a transmission mechanism divides driving force of one drive motor into two lines and it transmits to a feeding member and a regulating member, preventing part mark of a driving means from increasing, and increasing. In order that the invention according to claim 2 may solve an aforementioned problem, when said drive motor rotates normally, while driving force of this drive motor is transmitted, in the invention according to claim 1, one system of said transmission mechanism, It is characterized by constituting a system of another side of said transmission mechanism so that driving force of this drive motor may be transmitted, when said drive motor is reversed, and switching contact and a separated location of said feeding member and a regulating member with reciprocal rotation of this drive motor.

[0009]In that case, since a feeding member and a regulating member can be driven with reciprocal rotation of a drive motor, a feeding member and a regulating member can be driven with easy composition which has one drive motor. In order that the invention according to claim 3 may solve an aforementioned problem, in the invention according to claim 2 said transmission mechanism, A position which branches driving force of said drive motor for each system at least is equipped with a gear of a couple which has a one-way clutch, When said drive motor rotates normally, while rotating one side of said gear and transmitting driving force to either one of a feeding member and a regulating member, it is characterized by making it not transmit driving force to any of a feeding member and a regulating member, or the other, without rotating the other of a gear.

[0010]In that case, it can switch transmitting driving force of a drive motor to a feeding member or a regulating member by using a gear which has a one-way clutch as a transmission mechanism, a driving means can be simplified, and only the part can reduce a manufacturing

cost of an automatic manuscript conveying machine. In the invention according to any one of claims 1 to 3 in order that the invention according to claim 4 may solve an aforementioned problem, It is characterized by providing a part of member which constitutes a transmission mechanism of a to [ from said drive motor / said feeding member ] on a predetermined conveyance member which is allocated near the feeding member and feeds paper to a manuscript, and the same mind.

[0011]In that case, while being able to simplify composition of a driving means by being allocated near the feeding member and providing a part of member which constitutes a transmission mechanism on the existing conveyance member and the same mind, it can make it unnecessary to secure an excessive space for installing a transmission mechanism. Since a new member for supporting a part of transmission mechanism becomes unnecessary, a feed route of a manuscript, etc. can be prevented from being covered with a new member, and it can prevent interfering with work which removes a jam manuscript from a feed route.

[0012]

[Embodiment of the Invention]Hereafter, the embodiment of this invention is described based on a drawing. Drawing 1 - 14 are the figures showing one embodiment of the automatic manuscript conveying machine concerning this invention, and show the example which carries the automatic manuscript conveying machine of this invention in the copying machine as an image forming device. As an image forming device, it is applicable to a facsimile machine, a printer, etc. other than a copying machine.

[0013]First, composition is explained. In drawing 1 and 2, 1 is a copying machine and the contact glass 2 is formed in the upper surface of this copying machine 1. The automatic manuscript conveying machine (only henceforth ADF) 3 is formed in the upper part of the copying machine 1, and this ADF3 is connected via the hinge etc. which are not illustrated to the copying machine 1 so that the contact glass 2 may be opened and closed.

[0014]The manuscript tray 4 as a manuscript mounting base with which this ADF3 can lay the manuscript sheaf P which consists of two or more manuscripts, The separation and the feeding means 5 which conveys the separated manuscript toward the contact glass 2 after separating [ each ] one manuscript from the manuscript sheaf laid in the manuscript tray 4, While making the exposure position on the contact glass 2 convey and suspend the manuscript conveyed toward the contact glass 2 by separation and the feeding means 5, Carrying in and the carrying means 6 which takes out the manuscript which reading ended by the reading means (a publicly known exposure lamp, a mirror, a lens, CCD, etc.) of the copying machine 1 allocated under the contact glass 2 from the contact glass 2, It is \*\* constituted with the ejecting means 7 which delivers the manuscript taken out from the exposure position of the contact glass 2 by carrying in and the carrying means 6 to either of the 2nd delivery trays 9 allocated under the 1st delivery tray 8 or the manuscript tray 4 which

projects from the side of the copying machine 1. The 1st delivery tray 8 may be formed so that it may project from the side of ADF3. The picture read and \*\* carried out by the reading means is transferred by the recording form by the image forming means of a publicly known photo conductor drum, a developer, etc.

[0015]Separation and the feeding means 5 Call Collo 10 (feeding member), the feed belt 11, the reverse koro 12, pullout drive Collo 13, pullout follower Collo 13a, It comprises 13b, the stoper claw (regulating member) 14, the manuscript set sensor 15, the pullout sensor 16, and the resist sensor 17. The stoper claw 14 is formed movable between the regulated position (contact position) which contacts the manuscript tray 4, and the retreating position (separated location) evacuated from the manuscript tray 4, When located in a regulated position, it regulates that the manuscript sheaf P moves to the transportation direction downstream rather than the prescribed position on the manuscript tray 4 in contact with the tip part of the manuscript sheaf P.

[0016]Call Collo 10 is established in the manuscript sheaf P so that contact and isolation are possible, paper is fed to the manuscript located in the upper layer from the manuscript sheaf P, and the feed belt 11 and the reverse koro 12 separate only the top manuscript from this manuscript sheaf P. This separated manuscript is pinched by pullout drive Collo 13 and pullout follower Collo 13a and 13b which is taken to this and the surroundings carry out, is drawn out from the feed belt 11 and the reverse koro 12, and is conveyed toward the contact glass 2.

[0017]And these call Collo 10, the feed belt 11, the reverse koro 12, pullout drive Collo 13, and the stoper claw 14 are driven with the 1st drive mechanism (driving means) 18 and the 2nd drive mechanism 19 which are shown in drawing 2. The 1st drive mechanism 18 has the calling motor (drive motor) 20 which consists of stepping motors, as shown in drawing 2 - 4, and it drives this calling motor 20 with the main controller 21. The driving force of this motor 20 is transmitted to the gear 23 via the belt 22 with which the gear tooth was formed in the inner periphery from the gear 20a attached to the output shaft of the motor 20, and this gear 23 is connected with the pickup input toothed wheel 25 via the shaft member 24. This gear 25 meshes with the pickup driver 26 and the stopper gear 27, a one-way clutch is built in these gears 26 and 27, and it rotates only to one way with this one-way clutch. These gears 26 and 27 are equivalent to the gear provided in the position which branches for each system in the driving force of the drive motor (call motor 20) said by a claim.

[0018]If the calling motor 20 rotates among drawing 2 and 3 to the CCW direction which is a clockwise rotation, the pickup driver 26 will rotate via the belt 22 and the pickup input toothed wheel 25 counterclockwise (here, since drawing 3 and drawing 4 have opposite direction, a hand of cut is explained based on drawing 2 and 3). At this time, rotation of the pickup input toothed wheel 25 is not transmitted with a one-way clutch to the stop gear 27.

[0019]The pickup driver 26 is connected to the cam 31 via the driving shaft 29 in which the

home position detection filler 28 was fixed. The driving shaft 29 is supported by the brackets 110 and 111 formed in the main part 1a of the copying machine 1, enabling free rotation. The one-way clutch 30 was attached to this driving shaft 29, this clutch 30 was fixed to the bracket 111, and the cam 31 is prevented from being reversed by the idling torque of the one-way clutch built in the pickup driver 28.

[0020] The filler 28 is detected by the detecting sensor 32. This sensor 32 comprises a photosensor which consists of a light emitting device and a photo detector, when the light irradiated by the photo detector from a light emitting device by the filler 32 is intercepted, is called so that the rotating position of the cam 31 may be detected and mentioned later, and detects the home position of Collo 10.

[0021] The lever 33a attached to the end of the pickup driving member 33 is contacted, and the cam 31 is isolated on it. This driving member 33 will be rotated centering on the driving shaft 34, if it is slidably attached on the same axle at the feed belt driving shaft 34 which drives the feed belt 11 as shown in drawing 5 and 6, and the cam 31 contacts the lever 33a.

[0022] Although the driving member 33 does not need to be formed in the driving shaft 34 and the same axle, if it does in this way, it can simplify the composition of the parts of a feed conveying path, and can raise the removal nature of the jam manuscript on the carrying path of separation and the feeding means 5. While calling to this driving shaft 33, calling via the Collo rocking member 35 and attaching Collo 10, the idle wheel 37 is attached. The idle wheel 37 was connected to the gear 36a attached to the end of the feed belt driven shaft 36 which drives the feed belt 11 via the gear 10a formed in the end of call Collo 10, and these gears 10a, 37, and 36a always mesh.

[0023] Call Collo 10 has fallen caudad with prudence, and usually serves as a position in which this state conveys a manuscript in contact with the manuscript sheaf P (refer to drawing 6 (a)). If the cam 31 contacts the lever 33a, it is the position which the driving member 33 rotated centering on the driving shaft 34, and called via the rocking member 35, and pushed up Collo 10 up, and was made to move in it, and this state isolated from the manuscript sheaf P (refer to drawing 6 (b)).

[0024] If feed Collo 10 is made the cam 31, while the lever 33b provided in the other end of the driving member 33 will be isolated from the stopper 38a formed in the bracket 38 which stores the feed belt 11. If it calls with prudence and Collo 10 moves to a contact position, the lever 38a will call in contact with the stopper 38a, and will regulate the falling position of Collo 10.

[0025] When it descends so that call Collo 10 may contact the manuscript sheaf P, the detecting sensor 32 detects the filler 28 and the sensor 28 outputs a signal to the main controller 21 at this time. The main controller 21 is called based on this detection information, and Collo 10 judges it to be what was located in the contact position. On the other hand, if the calling motor 20 rotates among drawing 2 and 3 to the CW direction which is a

counterclockwise rotation, the stopper gear 27 will rotate clockwise via the belt 22 and the pickup input toothed wheel 25. At this time, with the one-way clutch, rotation of the pickup input toothed wheel 25 was not transmitted, and the pickup driver 26 is come.

[0026]The driving shaft 39 is attached to the stopper gear 27, and the cam 40 and the home position detection filler 41 are attached to this driving shaft 39. The driving shaft 39 is established in parallel with the driving shaft 42, and the stoper claw 14 is attached to the driving shaft 42. The lever 42a is formed in the end of the driving shaft 42, and the contact and isolation of the cam 40 on the lever 42a are attained with rotation of the driving shaft 39. The lever 42a is pulled by the spring 43, if it is pulled by the spring 43 as shown in drawing 7 (a), will rotate the driving shaft 42 to a determined direction, and will move the stoper claw 14 to the retreating position isolated from the tip of a manuscript.

[0027]If the cam 40 pushes in the lever 42a in contact with the lever 42a, It moves to the regulated position where the rotating shaft 42 resists the pull strength of the spring 43, it moves to a determined direction and a counter direction, and the stoper claw 14 contacts at the tip of the manuscript sheaf P in contact with the manuscript tray 4 at this time. The belt 22, the gear 23, the shaft member 24, the gears 23, 26, and 27, the driving shaft 29, the cam 31, the pickup driving member 33, the driving shaft 34, and the driving shaft 39 constitute the transmission mechanism 120 which divides the driving force of the calling motor 20 into two lines, and transmits it from this embodiment, The rocking member 35 and the cam 40 are formed in the outgoing end of each system of the transmission mechanism 120, and constitute the member turning which calls according to the drive of each system of the transmission mechanism 120, and moves Collo 10 and the stoper claw 14 to contact and a separated location.

[0028]The detection filler 41 is detected by the filler detection sensor 44. This sensor 44 comprises a photosensor which consists of a light emitting device and a photo detector, when the light irradiated by the photo detector from a light emitting device by the filler 41 is intercepted, detects the rotating position of the cam 40 and outputs a signal to the main controller 21. When the stoper claw 14 is in the retreating position shown in drawing 7 (a), the detecting sensor 44, A signal is outputted to the main controller 21, when this signal inputs, it judges that the main controller 21 has the stoper claw 14 in a retreating position, and when this signal does not input, it is judged that it has the stoper claw 14 in a regulated position.

[0029]The feed belt 11 is wound around the feed belt driving shaft 34 and the feed belt driven shaft 36, enabling free circumference movement, as shown in drawing 5, and 6 and 8, and this driving shaft 34 and driven shaft 36 are engaging with the bracket 38. The cylindrical member 45 is inserted in the inside and, as for the driven shaft 36, the springs 46a and 46b are provided contractingly between the both ends of this cylindrical member 45, and the bracket 38. These springs 46a and 46b by energizing the driven shaft 36 in the direction isolated from

\*\*\*\*\* 34, Fixed tension is given to the feed belt 11 by forcing on the bracket 38 the bearings 47a and 47b provided in the both ends of the driven shaft 36 via the feed belt 11.

[0030]By contracting the springs 46a and 46b, as tension is not given to the feed belt 11, the feed belt 11, the driving shaft 34, and the driven shaft 36 can be removed from the bracket 38. The cylindrical member 45 is inserted in the rod 35a provided in the rocking member 35, and moves the rocking member 35 by rocking centering on the driving shaft 34 between the position to which call Collo 10 contacts the manuscript sheaf P, and the isolated position.

[0031]Thus, while the stoper claw 14 moves between retreating positions with the one calling motor 20, call Collo 10 moves between a retreating position and a contact position. When the Koppies Tart signal inputs two or more sets from the main part of 1, the main controller 21 drives the calling motor 20, is called while it moves the stoper claw 14 to a retreating position, and makes the 1st drive mechanism 18 drive so that Collo 10 may be moved to a contact position.

[0032]On the other hand, the 2nd drive mechanism 19 has the feed motor 48 driven based on the command signal from the main controller 21 as shown in drawing 2, The driving force of this feed motor 48 is transmitted to the transfer gear 55 via the gear 49, the belt 50, the gears 51 and 52, the belt 53, and the gear 54, respectively. It has geared with the gear 56 which transmits driving force to the feed belt driving shaft 34 on this transfer gear 55, and the one-way clutch is built in this gear 56.

[0033]On the gear 55, the gear 57 in which one-way CHIRATCHI was built meshes, and this gear 57 drives the reverse koro 12 via the gear 58. The transfer gear 55 drives pullout drive Collo 13 via the gears 59, 60, 61, 62, 63, and 64. The clutch 64a is formed between pullout drive Collo 13 and the gear 64, and this clutch 64a is based on the command signal from the main controller 21, and transmits and intercepts the driving force from the gear 64 to pullout drive Collo 13. The one-way clutch is built in the gear 59. A thin arrow shows transfer of driving force when the calling motor 20 rotates to a CW direction among drawing 2, and a thick arrow shows transfer of driving force when the calling motor 20 rotates to a CCW direction.

[0034]The main controller 21 drives the feed motor 48 based on the detection information from the manuscript set sensor 15, the pullout sensor 16, and the resist sensor 17. This pullout sensor 16 continues crosswise [ of a manuscript ], is formed, and can also detect the crosswise length of a manuscript. [ two or more ] When the Koppies Tart signal inputted two or more sets from the main part of 1 and it specifically detects that the main controller 21 has the manuscript sheaf P on the manuscript tray 4, After driving the calling motor 20 to a CW direction and moving the stoper claw 14 to a retreating position, the calling motor 20 is driven and called to a CCW direction, and the 1st drive mechanism 18 is made to drive so that Collo 10 may be moved to a contact position.

[0035]If the feed motor 48 rotates successively in this operation in the CW direction which is

the direction of a counter clockwise, this torque will be transmitted to the transfer gear 55 via the gear 49, the belt 50, the gears 51 and 52, the belt 53, and the gear 54, and the transfer gear 55 will rotate counterclockwise. When rotating in this direction, the gear 56 rotates and circumference movement of the feed belt 11 is carried out clockwise. When the transfer gear 55 rotates counterclockwise, in order for the gear 57 to also rotate, this rotation is transmitted to the reverse koro 12 via the gear 58, and the reverse koro 12 rotates counterclockwise.

[0036]For this reason, in order that the reverse koro 12 may move in the feed inhibition direction while the feed belt 11 carries out circumference movement in the feeding direction of a manuscript after feeding of the manuscript sheaf P is started by call Collo 10 where driving force is transmitted from the feed belt driving shaft 34, \*\*\*\*\* located in the top is separated from the manuscript sheaf P to which paper was fed. Since driving force is transmitted to pullout drive Collo 13 via the gears 59, 60, 61, 58, 62, 63, and 64 from the transfer gear 55, Pullout drive Collo 13 feeds paper to the manuscript which rotated counterclockwise and was separated by this Collo 13 and pullout follower Collo 13a and 13b.

[0037]If the tip of this manuscript is detected by the pullout sensor 16, after driving and calling the calling motor 20 to a CCW direction and moving Collo 10 to a retreating position, the feed motor 48 is driven to the CW direction which is a clockwise rotation. Since the transfer gear 55 rotates clockwise at this time, as for the gears 56 and 57, the rotation from the transfer gear 55 is not transmitted, but the feed belt 11 is stopped by the one-way clutch. However, while the transfer gear 55 drives pullout drive Collo 13 via the gears 59, 60, 61, 62, 63, and 64, A manuscript is conveyed toward the contact glass 2 by pullout drive Collo 13, preventing separation of the manuscript which follows by the reverse koro 12, since the reverse koro 12 is driven via the gears 59, 60, 61, and 58.

[0038]A manuscript is conveyed by this contact glass 6 by carrying in and the carrying means 6. This carrying in and carrying means 6 have the transportation belt 65, and this transportation belt 65 is wound around the transportation belt driving roller 66 and the transportation belt follower roller 67. The transportation belt driving roller 66 is driven with the 3rd drive mechanism 68. This 3rd drive mechanism 68 has the transportation belt motor 69, and drives this motor 69 with the main controller 21, Transmitting driving force to the transportation belt driving roller 66 via the gear 70, the belt 71, the gears 72 and 73, the belt 74, and the gear 75, in connection with right and counterrotation of the motor 69, as for the transportation belt driving roller 66, right and counterrotation carry out the transportation belt 65.

[0039]This carrying in and carrying means 6 make the CCW direction which is a counterclockwise rotation carry out positive rotation of the transportation belt motor 69 with the command signal from the main controller 21, when the feed motor 48 rotates reversely to a CCW direction and suspends the drive of the feed belt 11. For this reason, the manuscript from

which the transportation belt 65 was separated by carrying out positive rotation by the 3rd drive mechanism 68 is carried in on the contact glass 2. And when the back end of the manuscript carried in to the contact glass 2 is detected by the resist sensor 17, the exposure position of the contact glass 2 is made to suspend a manuscript, when only a predetermined pulse carries out the normal rotation drive of the transportation belt motor 69 from this detection time.

[0040]And the drive of the feed motor 48 and the transportation belt motor 69 is suspended at this time. After the manuscript which follows from the manuscript in which the feed motor 48 drove to the CW direction again, and was laid on the manuscript tray 4 next was separated, When the resist sensor 17 detects the tip of this manuscript and only a predetermined pulse is conveyed from this detection time, the drive of the feed motor 48 is suspended, the manuscript which follows withdraws in advance, and operation is performed.

[0041]On the other hand, when a manuscript stops to the exposure position of the contact glass 2, reading and exposure of a manuscript are performed by the copying machine 1. Since a signal is inputted into the main controller 21 from the copying machine 1 after this reading and exposure are completed, if this signal inputs the controller 21, a manuscript will be taken out by the ejecting means 7 from the contact glass 2 by carrying out the normal rotation drive of the transportation belt motor 69 again.

[0042]The ejecting means 7 Inversion driving Collo 81, delivery follower Collo 82, the inversion guide koro 83, reversal follower Collo 84, the 1st switching claw 85, the 2nd switching claw 86, delivery drive Collo 87, delivery follower Collo 88, and the delivery sensor 89a, Inversion driving Collo 81, delivery drive Collo 87, and the 1st and 2 change nails 85 and 86 are driven with the 4th drive mechanism 90 from 89b. The 4th drive mechanism 90 has the delivery motor 91 driven with the command signal from the main controller 21, and the gear 92 is connected to the output shaft 91a of this delivery motor 91 via the belt 91b. This gear 92 transmits driving force to the gears 93, 94, and 95 via the belt 96, respectively, and inversion driving Collo 81 and delivery drive Collo 87 are connected to the gears 95 and 96, respectively.

[0043]While the 1st change nail 85 is rocked by the 1st solenoid 97, the 2nd change nail 86 is rocked by the 2nd solenoid 98. These the 1st and 2 solenoids 97 and 98 are turned on and off by the command signal from the main controller 21. Specifically, the 1st switching claw 85 is in the contact glass 2 and the state where it has stood by in the foambow JISHON position (the undersurface of the switching claw 85 constitutes a part of carrying path of a manuscript) which opens the 1st delivery tray 8 for free passage, by the 1st solenoid 97 at the time of the delivery of an one side manuscript.

[0044]While the main controller 21 makes the 1st switching claw 85 stand by to a home position, without driving the 1st solenoid 97 at the time of the one side mode in which the usual one side manuscript is conveyed, At the same time as it drives the transportation belt motor 69 after reading of a manuscript and the end of exposure, the delivery motor 91 is made to drive.

For this reason, paper is linearly delivered to the manuscript pinched by inversion driving Collo 81 and reversal follower Collo 82, without a surface and rear surface being reversed by the 1st delivery tray 8.

[0045]When double-side mode is specified on the other hand by the final controlling element by which the main controller 21 was formed in the copying machine 1 and which is not illustrated, By driving the 1st solenoid 97, while making it move to the position which opens the contact glass 2 and the inverting path 101 for free passage from a home position (the upper surface of the switching claw 85 constitutes a part of carrying path of a manuscript as shown in drawing 1), the 1st switching claw 85, At the same time as it drives the transportation belt motor 69 after reading of one side of a double-sided manuscript, and the end of exposure, the delivery motor 91 is made to drive. For this reason, a manuscript is guided at the inverting path 101 pinched by inversion driving Collo 81 and delivery follower Collo 82, and is conveyed by the inversion guide koro 83 toward the 2nd switching claw 86.

[0046]When the manuscript which drove the 2nd switching claw 86 by the 2nd solenoid 98, and reading of one side ended is taken out from the contact glass 2, It switches to the foambow JISHON position (as shown in drawing 1, the undersurface of the 2nd switching claw 86 constitutes a part of carrying path of a manuscript) which opens for free passage the inverting path 101 and the return route 102 established between the contact glass 2, without driving by the 2nd solenoid 98.

[0047]For this reason, after the manuscript taken out from the contact glass 2 is conveyed by the inverting path 101 with the 1st switching claw 85, by the 2nd switching claw 86, after the surface and rear surface has been reversed by the return route 102, it is pinched by inversion driving Collo 81 and reversal follower Collo 84b, and is returned to the contact glass 2. If the tip of a manuscript is detected by the delivery sensor 89b formed on the inverting path 101, The main controller 21 carries out the reverse drive of the transportation belt motor 69, and carries out the reverse drive of the transportation belt 65, When the rotation pulse of the transportation belt motor 69 from the time of the tip of a manuscript being detected by the delivery sensor 89b reaches a predetermined value, it judges that the manuscript was conveyed to the exposure position on the contact glass 2, and the transportation belt motor 102 is stopped.

[0048]Since a signal is inputted into the controller 21 from the copying machine 1 after reading and exposure of a manuscript are completed in an exposure position, If this signal inputs the controller 21, the normal rotation drive of the transportation belt motor 69 will be carried out, While the drive of the 2nd solenoid 98 is suspended while driving the 1st solenoid 97, and making the contact glass 2 and the inverting path 101 open for free passage with the 1st switching claw 85, By making the return route 102 and the 2nd delivery tray 9 open for free passage with the 2nd switching claw 86, (The upper part of the 2nd switching claw 86 constitutes a part of carrying path of a manuscript), After the manuscript taken out from the

contact glass 2 is pinched and conveyed in inversion driving Collo 81 and reversal follower Collo 82, it is pinched by delivery drive Collo 87 and delivery follower Collo 88, and paper is delivered to it on the 2nd delivery tray 9.

[0049]On the other hand, the manuscript set sensor 15, the pullout sensor 16, and the resist sensor 17 which were mentioned above constitute a manuscript detection means to detect the existence of the manuscript on the carrying path 105 of the manuscript having contained the manuscript tray 4, The main controller 21 constitutes the control means which controls movement of the stoper claw 14 based on the detection information from these manuscript set sensor 15, the pullout sensor 16, and the resist sensor 17.

[0050]When the main controller 21 specifically has a manuscript on the carrying path 105 of the manuscript tray 4, and separation and a feeding means 5 at the time of the injection of the power supply of the copying machine 1, When it is detected that the stoper claw 14 is located in a regulated position based on the detection information from the filler detection sensor 44, The calling motor 20 is driven, and when it is detected that move the stoper claw 14 to a retreating position, and the stoper claw 14 is located in a retreating position with the 1st drive mechanism 18, control which locates the stoper claw 14 in a retreating position as it is performed.

[0051]In this embodiment, the cover opening and closing 103 which can be opened and closed freely is formed in the separation and feeding means 5 side of the main part 3a of ADF3 to the main part 3a so that the carrying path 105 on separation and the feeding means 5 may be exposed and blockaded, The cover-opening-and-closing detection sensor 104 which detects the switching condition of this cover opening and closing 3 on the main part 3a near the covering 103, and outputs detection information to the main controller 21 is formed, and this sensor 104 comprises a photosensor, a touch sensor, etc. Pullout follower Collo 13a and 13b is attached to the cover opening and closing 103, enabling free rotation.

[0052]And while the main controller 21 detects that the cover opening and closing 103 was wide opened based on the detection information from the sensor 104, When the stoper claw 14 detects being located in a regulated position irrespective of the existence of the manuscript on the carrying path 105 of the manuscript tray 4, and separation and a feeding means 5, The stoper claw 14 is moved to a retreating position, and when it is detected that the stoper claw 14 is located in a retreating position, the stoper claw 14 is located in a retreating position as it is.

[0053]While detecting what the cover opening and closing 103 closed based on detection information from the sensor 104, When it detects that there is no manuscript on the carrying path 105 of the manuscript tray 4, and separation and a feeding means 5 and the stoper claw 14 detects being located in a retreating position, The stoper claw 14 is moved to a regulated position, and when it is detected that the stoper claw 14 is located in a regulated position, the

stoper claw 14 is located in a regulated position as it is.

[0054]While detecting what the cover opening and closing 103 closed based on the detection information from the sensor 104, When it detects that a manuscript is on the carrying path 105 of the manuscript tray 4, and separation and a feeding means 4 and the stoper claw 14 detects being located in a regulated position, The stoper claw 14 is moved to a retreating position, and when it is detected that the stoper claw 14 is located in a retreating position, the stoper claw 14 is located in a retreating position as it is.

[0055]Next, based on the flow chart shown in drawing 9 - 14, the conveying operation of a manuscript and position control operation of the stoper claw 14 of this embodiment are explained. This flow chart is the feeding operation program provided in the main controller 21. Here, the conveying operation of an one side manuscript is explained. First, the manuscript sheaf P is laid on the manuscript tray 4, and if the printing key provided in the final controlling element of the copying machine 1 is pressed and a feed signal is transmitted to the main controller 21 from the main part of the copying machine 1, the program of the main controller 21 will shift to a feeding operation routine.

[0056]First, when it distinguishes whether the number of the manuscripts to which paper is fed is the 1st (Step S1) and it is judged to be that whose number is the 1st, while making the feed clutch 64a turn on, a CW direction is made to rotate the calling motor 20 in drawing 9 (Step S2). If the CW direction which is a counterclockwise rotation is made to rotate the calling motor 20, the stopper gear 27 will rotate clockwise via the belt 22 and the pickup input toothed wheel 25. At this time, with the one-way clutch, rotation of the pickup input toothed wheel 25 was not transmitted, and the pickup driver 26 is come.

[0057]When the stopper gear 27 rotates, it is made to move to the retreating position which the cam 40 is isolated from the lever 42a, and isolates the stoper claw 14 from the tip of a manuscript as the lever 42a is pulled by the spring 43, the driving shaft 42 is rotated to a determined direction and it is shown in drawing 7 (a). And it judges that whether the stoper claw 14 moved to the retreating position moved to the retreating position when it distinguished (Step S3) and the detection filler 41 was detected by the filler detection sensor 44, and the reverse drive of the calling motor 20 is carried out to a CCW direction (step S4). At this time, driving force is transmitted to the pickup driver 26 via the belt 22 and the pickup input toothed wheel 25 from the calling motor 20. At this time, rotation of the pickup input toothed wheel 25 is not transmitted with a one-way clutch to the stop gear 27.

[0058]Subsequently, if the pickup driver 26 rotates, it will isolate and call from the lever 33a of the pickup driving shaft 33 by the cam 31, and Collo 10 will be moved to the contact position which contacts the manuscript sheaf P with prudence. When it distinguishes whether the stoper claw 10 moved to the contact position at this time (Step S5) and the detection filler 28 is detected by the filler detection sensor 32, call Collo 10 judges that it moved to the contact

position, and suspends the drive of the calling motor 20 (Step S6).

[0059] Subsequently, a CCW direction is made to rotate the feed motor 48 and the transportation belt motor 69. (Step S7). After paper is fed to the manuscript sheaf P by call Collo 10 at this time, the manuscript located in the top is separated from the manuscript sheaf P by the feed belt 11 and the reverse koro 12, and this separated manuscript is conveyed by pullout drive Collo 13 toward the contact glass 2.

[0060] Subsequently, when it does not distinguish and (Step S8) turn on whether the tip of the manuscript was detected by the pullout sensor 16, having been set to jam detection distinguishes whether carried out specified time elapse (step S9). And even if it carries out specified time elapse, when the tip of a manuscript is not detected, jam detection is performed in the pullout sensor 16 as what a manuscript has not reached, and feeding operation is interrupted (Step S10). On the other hand, when the tip of a manuscript is detected by the pullout sensor 16 at Step S8, the reverse drive of the feed motor 48 is carried out, and the calling motor 20 is driven to a CCW direction (Step S11).

[0061] At this time, without transmitting driving force to the feed belt 11 by the 2nd drive mechanism 19, Driving force is transmitted only to the pullout driving roller 13 and the reverse koro 12, and a manuscript is conveyed by pullout follower Collo 13 toward the contact glass 2, without performing separation of the manuscript mentioned later. If the calling motor 20 is driven to a CCW direction, in contact with the lever 33a, the driving member 33 rotates centering on the driving shaft 34, the cam 31 calls via the rocking member 35, Collo 10 will be pushed up up, and will be moved, and call Collo 10 will be moved to the retreating position isolated from the manuscript sheaf P to the upper part.

[0062] Subsequently, when it distinguishes whether call Collo 10 moved to the retreating position based on the detection information from the filler detection sensor 32 (Step S12) and call Collo 10 moves to a retreating position, the drive of the calling motor 20 is suspended (Step S13). Subsequently, it distinguishes whether the resist sensor 17 turned on, and when the resist sensor 17 does not turn on, having been set to jam detection distinguishes whether carried out specified time elapse (Step S15).

[0063] And even if it carries out specified time elapse, when the tip of a manuscript is not detected, jam detection is performed to the resist sensor 17 as what a manuscript has not reached, and feeding operation is interrupted (Step S16). carrying out the accelerating drive of the feed motor 48 on the other hand, when the tip of a manuscript is detected by the resist sensor 17 at Step S14 -- up to number of rotations equivalent to the transportation belt motor 69 -- top \*\* -- last (Step S17).

[0064] Subsequently, after transmitting the crosswise length of a manuscript to the copying machine 1 based on the detection information from the pullout sensor 16 (Step S18), It distinguishes whether the pullout sensor 16 turned off (Step S19), and when the pullout sensor

16 does not turn off, having been set to jam detection distinguishes whether carried out specified time elapse (Step S20). And even if it carries out specified time elapse, when a manuscript continues being detected, jam detection is performed as that to which the manuscript stagnated around pullout sensor 16, and feeding operation is interrupted (Step S21).

[0065]On the other hand, when the back end of a manuscript is detected by the pullout sensor 16 at Step S19, based on the front-and-back-ends detection information on the manuscript by the pullout sensor 16, the length information of a manuscript is transmitted to the copying machine 1 side (Step S22). Subsequently, as shown in drawing 10, when it is not distinguished and (Step S23) turned off whether the resist sensor 17 turned off, having been set to jam detection distinguishes whether carried out specified time elapse (Step S24).

[0066]And even if it carries out specified time elapse, when a manuscript continues being detected, jam detection is performed as that to which the manuscript stagnated around resist sensor 17, and feeding operation is interrupted (Step S25). On the other hand, when the resist sensor 17 is OFF at Step S23, resist back end interrupt processing is performed (Step S26). This operation is operation which makes the exposure position of the contact glass 2 suspend a manuscript, when only a predetermined pulse carries out the normal rotation drive of the transportation belt motor 69 from the time of the back end of a manuscript being detected by the resist sensor 17.

[0067]Subsequently, when it distinguishes whether there is any following manuscript (S28) and there is no following manuscript after transmitting the stop signal of a manuscript to the copying machine 1 (Step S27), the feed clutch 64a is turned off and the calling motor 20 is driven to a CW direction (Step S29). At this time, when the cam 40 resists the pull strength of the spring 43 and pushes in the lever 42a, as shown in drawing 7 (b), the driving shaft 42 rotates and the stoper claw 14 moves to a regulated position from a retreating position.

[0068]Subsequently, it distinguishes whether the stoper claw 14 moved to the regulated position (Step S30), it judges that it moved to the retreating position when the detection filler 41 was no longer detected by the filler detection sensor 44, the calling motor 20 is suspended, and processing (Step S31) is ended. on the other hand, when there is the following manuscript at Step S28, it is shown in drawing 11 -- it withdraws in advance and operation is performed. In drawing 10, first, the calling motor 20 is moved to a CCW direction (Step S41), and call Collo 10 is moved to a contact position. Subsequently, it is distinguished whether it called based on the detection information from the filler detection sensor 32, and Collo 10 moved to the contact position (Step S42), When it moves, while suspending the drive of the calling motor 20, the feed motor 48 is rotated to a CCW direction, call Collo 10, the transportation belt 11, the reverse koro 12, and pullout drive Collo 13 are driven, and the manuscript on the manuscript tray (Step S43) 4 is separated.

[0069] Subsequently, when it is distinguished and (Step S45) detected by the resist sensor 17 whether the tip of the manuscript of a manuscript was detected, the reverse drive of the feed motor 48 is carried out (Step S45). Subsequently, the calling motor 20 is rotated to a CCW direction. For this reason, while call Collo 10 moves to a retreating position, a manuscript is conveyed by the driving force of only the pullout driving roller 13. Subsequently, when it judges that distinguished (S47) and whether it called based on the detection information from the filler detection sensor 32, and Collo 10 moved to the retreating position moved to the retreating position, the drive of the calling motor 20 is suspended (Step S48).

[0070] Subsequently, it stands by until suspend the drive of the feed motor 69, a manuscript (Step S50) withdraws in advance, it ends operation and a feed signal inputs from the copying machine 1, when it is distinguished and (Step S49) detected whether the resist sensor 17 detected the tip of the manuscript. When the number of manuscripts is not the 1st at Step S1, While progressing to Step S51 of drawing 9 and making a CW direction rotate the feed motor 48, a CCW direction is made to rotate the transportation belt motor 69, the manuscript which is withdrawing in advance and standing by is conveyed to the exposure position of the contact glass 2, and it shifts to processing of Step S17.

[0071] An end of this the operation of a series of will distinguish whether the manuscript was conveyed by the contact glass 2 as shown in drawing 12 (Step S52). Since a flag will be set in the memory which is not illustrated if a manuscript is conveyed by the contact glass 2 and exposure is performed at this time, based on this memory information, it is distinguished whether it is finishing [conveyance]. After driving the transportation belt motor 69 and the delivery motor 91 (Step S53) and taking out a manuscript from on the contact glass 2 with the transportation belt 65 case [conveyed], by conveyance drive Collo 81 and reversal follower Collo 82, a manuscript is pinched and a manuscript is conveyed.

[0072] Subsequently, when it is not distinguished and (Step S54) detected by the delivery sensor 89a whether the tip of the manuscript was detected, having been set to jam detection distinguishes whether carried out specified time elapse (Step S55). And even if it carries out specified time elapse, when the tip of a manuscript is not detected, jam detection is performed in the delivery sensor 89a as what a manuscript has not reached, and feeding operation is interrupted (Step S56).

[0073] When specified time elapse has not been carried out at Step S55, In the case of a small size manuscript, the transportation belt motor 69 distinguishes whether it is a stop of the manuscript by the feeding operation performed in parallel to delivery operation (Step S57), and it in affirmation, Since a manuscript may not be discharged along with the contact glass 2 top two or more sheets, the drive of the delivery motor 91 is suspended and processing (Step S58) is ended.

[0074] On the other hand, when the delivery sensor 89 turns on at Step S54, After carrying out

a delivery deceleration counter clearance (Step S59), based on the drive pulse of the transportation belt motor 69, it calculates having conveyed the distance which the specified quantity (this embodiment 15 mm) deducted rather than the length according to the size from the tip of a manuscript, While the rear end part of the manuscript is pinched by inversion driving Collo 81 and reversal follower Collo 82 so that paper may be delivered to a manuscript on the 1st delivery tray 8 and starting a slowdown of the delivery motor 91, the drive of the delivery motor 91 is suspended (Step S60, S61).

[0075]Subsequently, when it is not distinguished and (Step S62) turned off whether the delivery sensor 89 turned off, having been set to jam detection distinguishes whether carried out specified time elapse (Step S63). And even if it carries out specified time elapse, when a manuscript continues being detected, jam detection is performed as that to which the manuscript stagnated around delivery sensor 89a, and feeding operation is interrupted (Step S64).

[0076]On the other hand, when the delivery sensor 89 turns off, (Step S65), when progressing to the flow of drawing 13 and distinguishing whether specified time elapse was carried out after the slowdown of the delivery motor 91, and specified time elapse is carried out, after transmitting a delivery completion signal to the copying machine 1 (Step S66), a drive is suspended for the delivery motor 91 and processing is ended. Next, based on drawing 14, position control operation of the stoper claw 14 is explained.

[0077]First, it distinguishes whether the power supply of the copying machine 1 was switched on and the power supply was supplied to ADF3 (Step S71), and at this time, since the position of the stoper claw 14 is unknown, the position of the stoper claw 14 is checked for initial setting out. That is, when \*\*\*\*\* [ immediately after the injection of a power supply ] is distinguished at Step S71 and it is judged as that which is immediately after powering on, it shifts to A of drawing 9.

[0078]After performing processing of A, it is distinguished whether based on the detection information from the manuscript set sensor 15, the pullout sensor 16, and the resist sensor 17, a manuscript is on the carrying path 105 of separation and the feeding means 5, and the manuscript tray 4 (Step S73). And when it is judged as a thing without a manuscript, it is distinguished whether the stoper claw 14 is in a retreating position based on the detection information from the filler detection sensor 44 (Step S74).

[0079]When it judges that it does not have the stoper claw 14 in a retreating position at this time, Since the stoper claw 14 is in a regulated position, when it judges that considers it as a position as it is, and it is in a retreating position, It is distinguished whether the calling motor 20 was driven to the CCW direction, the stoper claw 14 was moved toward the regulated position (Step S75), and the stoper claw 14 moved to the regulated position based on the detection information from the filler detection sensor 44 (Step S76). And when it is judged as what the

stoper claw 14 moved to the regulated position, the drive of the calling motor 20 is suspended (Step S77).

[0080]On the other hand, when it judges that it has a manuscript at Step S73, it is distinguished whether the stoper claw 14 is in a regulated position based on the detection information from the filler detection sensor 44 (Step S79). When it judges here that it does not have the stoper claw 14 in a regulated position, Since the stoper claw 14 is in a retreating position, when it judges that considers it as a position as it is, and it has the stoper claw 14 in a regulated position, It is distinguished whether the calling motor 20 was driven to the CCW direction, the stoper claw 14 was moved toward the retreating position (Step S80), and the stoper claw 14 moved to the retreating position based on the detection information from the filler detection sensor 44 (Step S81).

[0081]When the stoper claw 14 judges it as what was located in the retreating position, the drive of the calling motor 20 is suspended (Step S82). Thus, when a manuscript is on the carrying path 105 of the manuscript tray 4, and separation and a feeding means 5 at the time of the injection of a power supply, When it is detected that the stoper claw 14 is located in a regulated position based on the detection information from the filler detection sensor 44, When it is detected that drive the calling motor 20, move the stoper claw 14 to a retreating position with the 1st drive mechanism 18, and the stoper claw 14 is located in a retreating position, In order to perform control which locates the stoper claw 14 in a retreating position as it is, While being able to prevent a manuscript from being caught in the stoper claw 14 irrespective of the existence of a jam manuscript at the time of the injection of a power supply and being able to remove a manuscript easily, it can be prevented from the stoper claw 14 colliding with a manuscript and damaging a manuscript.

[0082]It distinguishes whether on the other hand, when an initial was set up at Step S71, based on the detection information from the opening and shutting sensor 104, by the energization condition, the feed covering 103 was opened wide and it was blockaded, and only when the covering 103 is from an opened state in a closed state, processing after Step S73 is performed. Namely, while detecting what the cover opening and closing 103 closed based on detection information from the sensor 104, When it detects that there is no manuscript on the carrying path 105 of the manuscript tray 4, and separation and a feeding means 5 and the stoper claw 14 detects being located in a retreating position, When it is detected that move the stoper claw 14 to a regulated position, and the stoper claw 14 is located in a regulated position, Since it was made to locate the stoper claw 14 in a regulated position as it is, when the cover opening and closing 103 is closed after removal of a jam manuscript, When there is no manuscript on the carrying path 105 of the manuscript having contained the manuscript tray 4, the stoper claw 14 can be moved to a regulated position, and a manuscript can be easily set to the manuscript tray 4.

[0083]When a manuscript is laid under the stoper claw 14 after removal of a jam manuscript, the stoper claw 14 is changed into the state where you made it located in a retreating position freely, While it can be prevented from the stoper claw 14 colliding with a manuscript and damaging a manuscript, when the cover opening and closing 103 judges that it was from the closed state in the opened state at Step S78, processing after Step S79 is performed.

[0084]Namely, while detecting that the cover opening and closing 103 was wide opened based on detection information from the sensor 104, When the stoper claw 14 detects being located in a regulated position irrespective of the existence of the manuscript on the carrying path 105 of the manuscript tray 4, and separation and a feeding means 5, When it is detected that move the stoper claw 14 to a retreating position, and the stoper claw 14 is located in a retreating position, In order to locate the stoper claw 14 in a retreating position as it is, Even when the manuscript which is on the carrying path 105 having contained the manuscript tray 4 at the time of opening of the cover opening and closing 103 is small and detection is difficult, by moving the stoper claw 14 to a retreating position, A manuscript is easily removable while being able to prevent it from the stoper claw 14 colliding with a manuscript and damaging a manuscript.

[0085]As explained above, form the 1st one drive mechanism 18 driven in this embodiment so that call Collo 10 and the stoper claw 14 may be moved to contact and a separated location, and this 1st drive mechanism 18 The calling motor 20, The transmission mechanism 120 which divides the driving force of this calling motor 20 into two lines, and transmits it, Since it constituted from the rocking member 35 and the cam 40 which are provided in the outgoing end of each system of the transmission mechanism 120, call according to the drive of each system of the transmission mechanism 120, and move Collo 10 and the stoper claw 14 to contact and a separated location, The manufacturing cost of ADF3 can be prevented from being able to set a driving source to one, preventing the part mark of the 1st drive mechanism 18 from increasing, and increasing.

[0086]When the calling motor 20 rotates to a CW direction, while the driving force of the calling motor 20 is transmitted, one system (drive system after the gear 27) of the transmission mechanism 120, The system (gear 26 side) of another side of the transmission mechanism 120 is constituted so that the driving force of the calling motor 20 may be transmitted, when the calling motor 20 rotates to a CCW direction, Since it calls with reciprocal rotation of the calling motor 20 and the position of Collo 10 and the stoper claw 14 was switched, it can call with reciprocal rotation of the calling motor 20, and Collo 10 and the stoper claw 14 can be driven. For this reason, it can call with the easy composition which has the one calling motor 20, and Collo 10 and the stoper claw 14 can be driven.

[0087]The transmission mechanism 120 equips the position which branches the driving force of the calling motor 20 for each system with 26 which has a one-way clutch, and 27, When the

calling motor 20 rotates to a CW direction, while rotating the gear 27 and transmitting driving force to the stoper claw 14, When it calls without rotating the gear 26, and driving force is not transmitted to Collo 10 and the calling motor 20 rotates to a CCW direction, while rotating the gear 26, calling and transmitting driving force to Collo 10, Having made it not transmit driving force to the stoper claw 14, without rotating the gear 27 A sake, It can switch calling the driving force of the calling motor 20 by using the gears 26 and 27 which have a one-way clutch as the transmission mechanism 120, and transmitting to Collo 10 or the stoper claw 14, The 1st drive mechanism 18 can be simplified and only the part can reduce the manufacturing cost of ADF3.

[0088]Since it provided on the feed belt driving shaft 34 and the same mind, the part 33, i.e., the pickup driving member, of the member which constitutes the transmission mechanism 120 until it calls from the calling motor 20 and reaches Collo 10, While being able to simplify the composition of the 1st drive mechanism 18, it can make it unnecessary to secure the excessive space for installing the transmission mechanism 120. Since the new member for supporting a part of transmission mechanism 120 becomes unnecessary, the carrying path 105 can be prevented from being covered with a new member, and it can prevent interfering with the work which removes a jam manuscript from the carrying path 105.

[0089]

[Effect of the Invention]According to the invention according to claim 1, a driving source can be set to one, as a transmission mechanism divides the driving force of one drive motor into two lines and it transmits to a feeding member and a regulating member, The manufacturing cost of an automatic manuscript conveying machine can be prevented from preventing the part mark of a driving means from increasing, and increasing.

[0090]According to the invention according to claim 2, since a feeding member and a regulating member can be driven with reciprocal rotation of a drive motor, a feeding member and a regulating member can be driven with the easy composition which has one drive motor. According to the invention according to claim 3, it can switch transmitting the driving force of a drive motor to a feeding member or a regulating member by using the gear which has a one-way clutch as a transmission mechanism, a driving means can be simplified, and only the part can reduce the manufacturing cost of an automatic manuscript conveying machine.

[0091]According to the invention according to claim 4, while being able to simplify the composition of a driving means by being allocated near the feeding member and providing a part of member which constitutes a transmission mechanism on the existing conveyance member and the same mind, it can make it unnecessary to secure the excessive space for installing a transmission mechanism. Since the new member for supporting a part of transmission mechanism becomes unnecessary, the feed route of a manuscript, etc. can be prevented from being covered with a new member, and it can prevent interfering with the work

which removes a jam manuscript from a feed route.

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[Translation done.]